

Ampère Unité Mixte de Recherche CNRS

Génie Électrique, Électromagnétisme, Automatique, Microbiologie environnementale et Applications

State of the art of high switching frequency inductive DC-DC converters in SoC context

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Abstract

- Supplying large system on chip requires specific grid and is spread over multiple voltage domains. Each domain depends on a dedicated DC-DC. For the sake of integration, switch capacitor DC-DC seems to have the favors of designers but further increase in the switching frequency associated to a 3D approach gives back some competitiveness to inductive DC-DC converters.
- Some recent experiments in the +100 MHz switching frequency area demonstrate the interest of multiphase and coupled inductors. A global analysis of pertinent results as state of the art enables to draw similar conclusions and many other trends.
- Various landscapes have been populated with available figures in pertinent papers about implemented DC-DC converters. Trends are analyzed to exhibit design trade-offs and further extrapolations, focusing mainly on active devices.
- In the context of POWERSWIPE project, a 200 MHz DC-DC converter (3.3 V input voltage, 350 mW output power, 1.2 V to 0.6 V output voltage) is taken as a study case. Specifications are added in the landscape and the trend analysis orientates the converter architecture for 40 nm CMOS technology. Particularly, cascode-based power stage is analyzed and selected. Primary post-layout simulation results let hope more than 90% power efficiency. Passive devices are related to an interposer technology targeting the fabrication of magnetic devices on top of embedded capacitor banks.





- **Remember PowerSoC 2012**
- **♦ Inductive vs. capacitive (non-isolated) DC/DC**
- **♦ Why +100MHz switching frequency DC/DC?**
- **A** possible lecture of the state-of-the-art
- SpowerSWIPE proposal, early results
- **Perspectives**



PowerSoC 2012

- Now established: "power is not an afterthought of system"
- Specifications now common in essence
 - how to deliver as much Amps as possible in a given area, for a targeted quality of service, with the best efficiency and the lowest cost
- Higher expectations: losses < 10% of platform power + efficiency flatness
- SGlobal view: passives as important as actives
- Complex control schemes despite high switching frequency



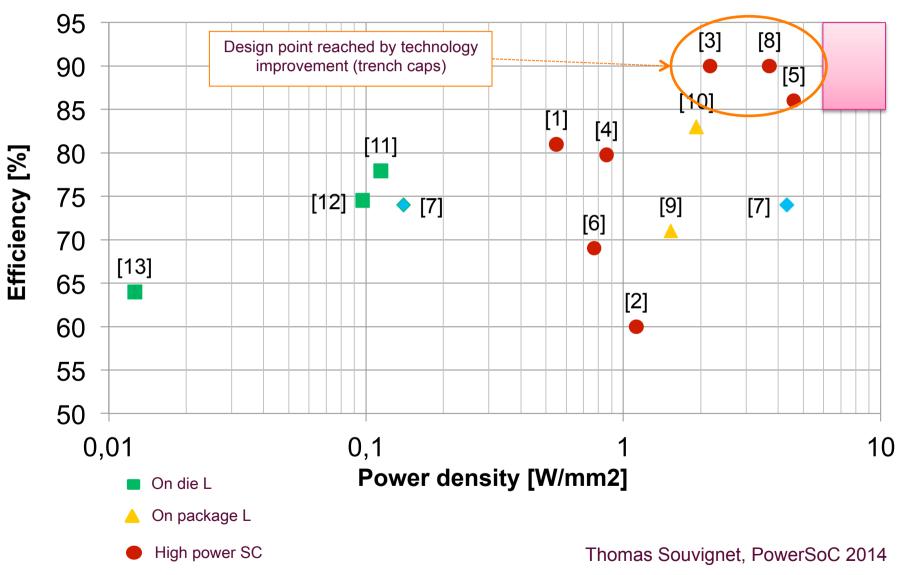
Non-isolated DC/DC converters

Inductive versus capacitive architectures

- SoA → efforts to push the limits
- SoC → heavy technology constraint
- V_{out}/V_{in} specification
- Necessity for a portfolio of solutions with various tradeoffs



Capacitive on-chip DC/DC



State of the art of high switching frequency inductive DC-DC converters



Non-isolated DC/DC converters

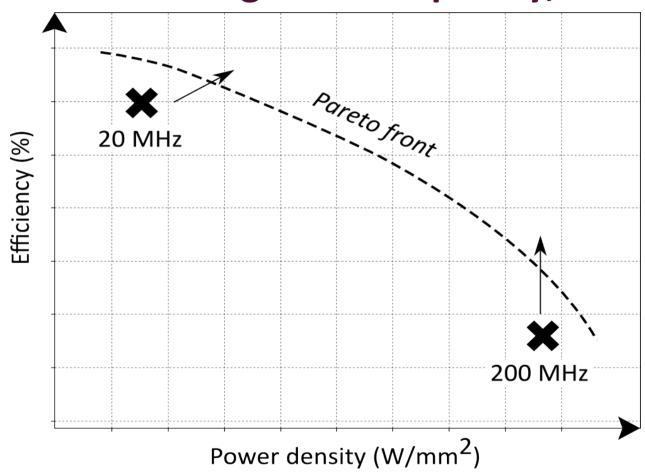
Why +100MHz switching frequency?

- Improvements in technology enables better active and passive devices
 mechanical increase in frequency thus in footprint
- Application requirements
 - large transient performances (EER, DVFS)
 - power density (smaller footprint)
- Mission profile (efficiency flatness)



Why +100MHz switching frequency?

♦ Losses → limit voltage and frequency, but...



J.W. Kolar et al., "PWM Converter Power Density Barriers", IEEE PCC, 2007



State-of-the-art of HF DC-DC

Silicon demonstrators

- Steady-state performances
- Transient performances, Power density aspects: no common benchmarks

Many metrics, unique FoM not pertinent → landscapes

Reference point :

[Burton et al., 2014] Fully integrated voltage regulators on 4th generation Intel core SoCs. In 29th Annual IEEE Applied Power Electronics Conference and Exposition (APEC), 2014, pages 432-439.

CIPS 2014: Neveu, F.; Martin, C.; Allard, B., "Review of high frequency, highly integrated inductive DC-DC converters", 8th International Conference on Integrated Power Systems (CIPS), 2014, pp.1-7, 25-27 Feb. 2014



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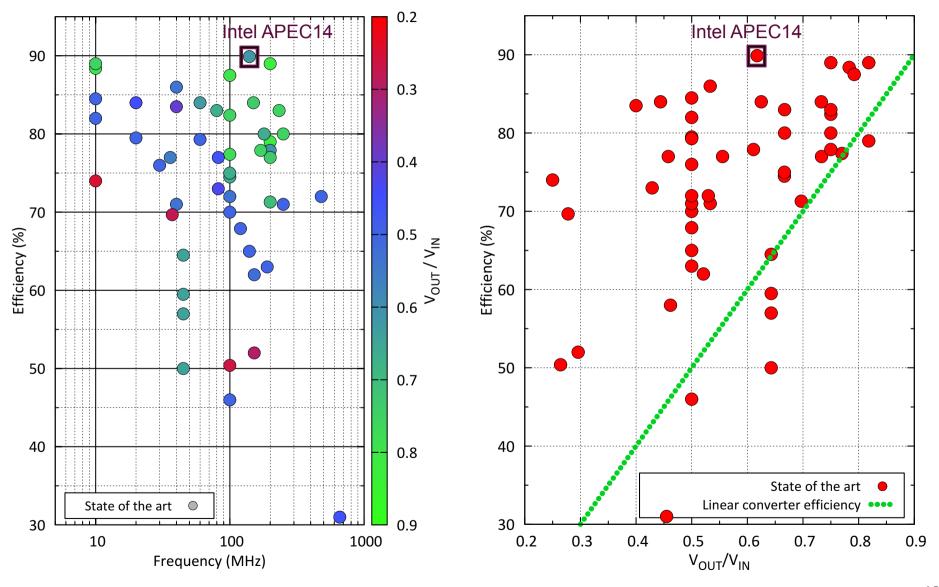
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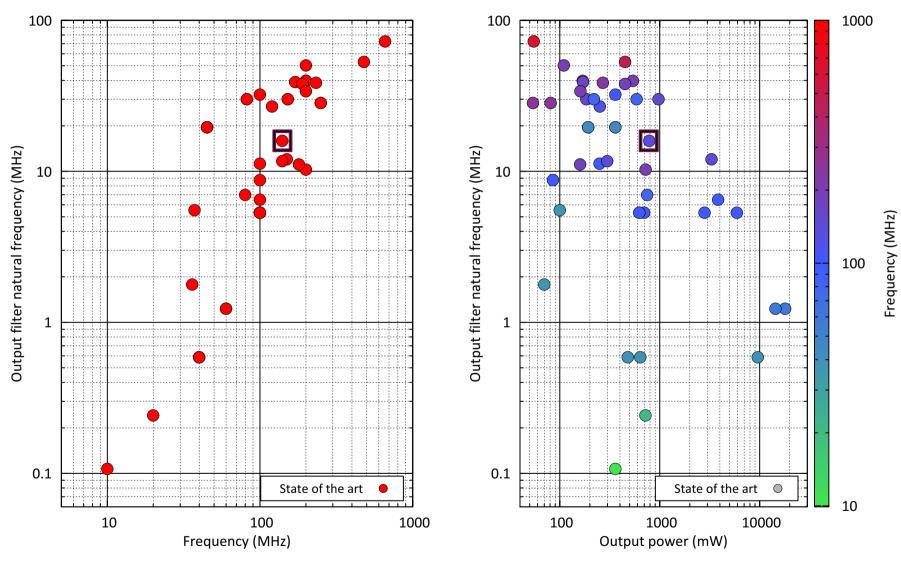


Efficiency, frequency and ratio



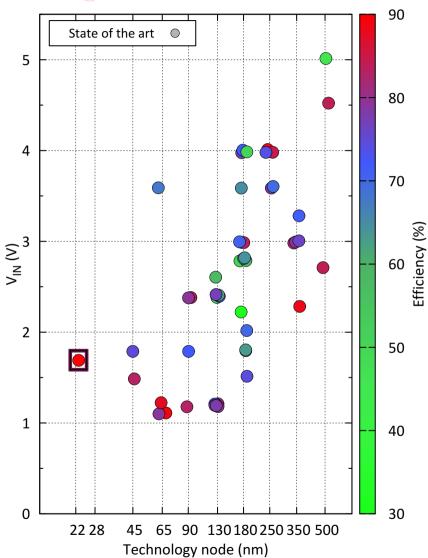


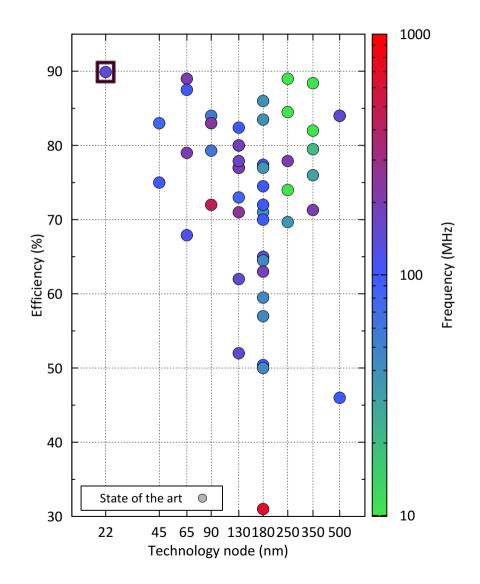
Output filter





Technology







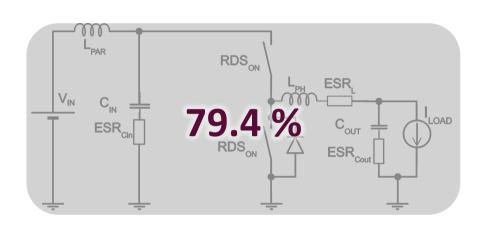
Control schemes

- Voltage mode versus current mode
- >PWM versus Hysteretic control or sliding mode control
- Digital versus analogue
 - 2 control loops (analogue control + digital supervisor)
 - Full digital low-losses controller demonstrated (limitations in transient performances)
- Systematic stability of closed-loop DC/DC quite complex (sample data modeling)
- **CAE** quite complex



Wrap-up

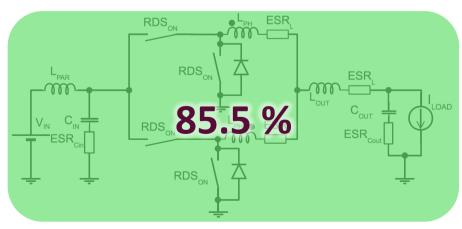
+100MHz switching frequency → phase coupling

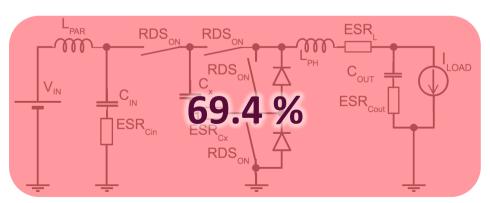


RDS_{ON}

Standard cell

2-phases





Coupled 2-phases

3-levels





♦ Efficiency flatness → phase shedding

Air inductors versus magnetic devices:

- Cost, complexity
- EMI is an issue
- Coupling of inductors → magnetic material

Separate issues, separate technologies

- Interposer of passive devices
- Enable trench capacitors

♦ Motivations for PowerSWIPE HF DC/DC



PowerSWIPE consortium

BOSCH

Tyndall National Institute, University College Cork

> IPDiA, Caen

Ampère Laboratory – University of Lyon, INSA Lyon, Lyon

Centro de Electrónica Industrial – Universidad Politécnica de Madrid Robert Bosch GmbH

> Infineon Technologies AG

Infineon Technologies Austria Villach AG

Tyndall

CETURM Centro de Electronica Industrial

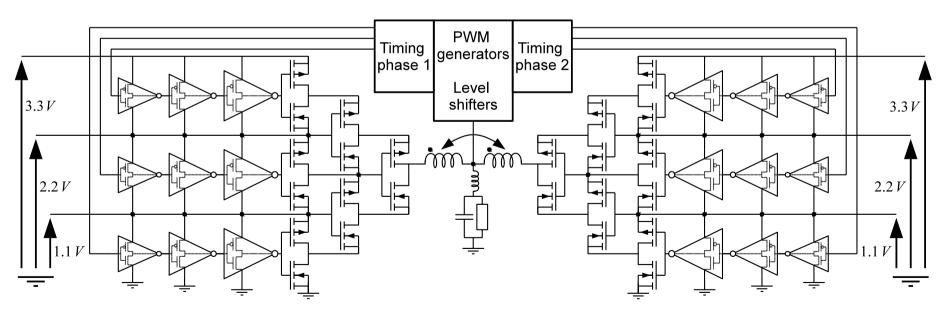


Schematic

Kursun, V., Narendra, S. G., De, V. K., & Friedman, E. G. (2005). Cascode monolithic DC-DC converter for reliable operation at high input voltages. Analog Integrated Circuits and Signal Processing, 42(3), 231-238 → evaluation by simulation

Peng et al., 2013, A 100 MHz two-phase four-segment DC-DC converter with light load efficiency enhancement in 0.18 μm CMOS. IEEE Trans. Circ. & Syst. I, 60(8):2213–2224.

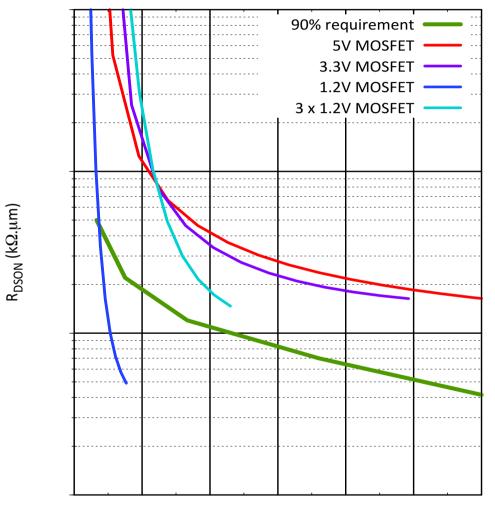
- 40nm bulk CMOS
- **♦ Interposer by IPDIA and Tyndall**
- **♦ Hard switching then Hysteretic control**



See details on design on poster #9 by Florian Neveu



Motivation for low-voltage MOSFET



Standard DC/DC step-down

- Analytical model of losses
- **Low-voltage MOSFET**
- Digital MOSFET could be considered
- Similar conclusions in any thin technology

Gate charge (fC.μm⁻¹)



400 350

300

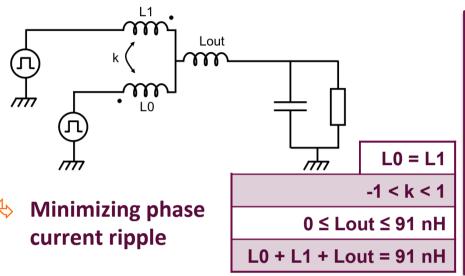
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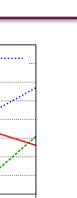
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Current (mA)

Local optimization of coupled inductors



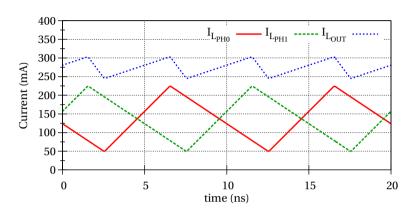


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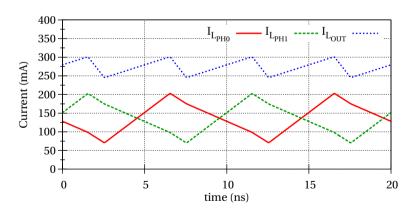
#2 : Lout = 0 nH, L0 = L1 = 45.5 nH, k = 0.4 **Ripple:** Phases: 151 mA, Output: 102 mA

10

time (ns)



#1: k = 0, L0 = L1 = 45.5 nH, Lout = 0 nH **Ripple:** Phases: 172 mA, Output: 56 mA

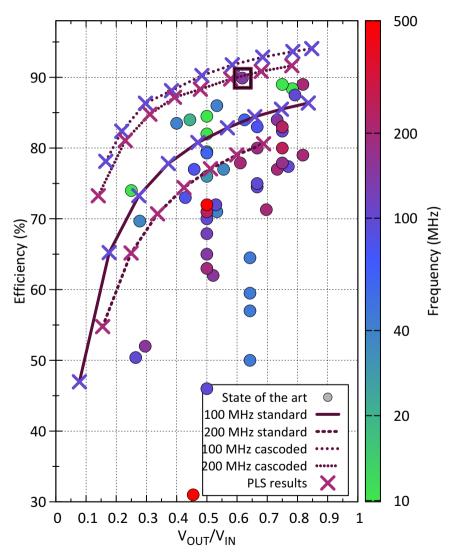


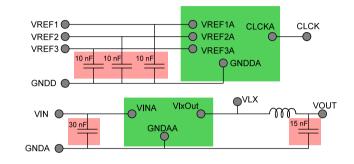
#3: L0 = L1 = 35 nH, Lout = 21 nH, k = 1 **Ripple:** Phases: 123 mA, Output: 55 mA

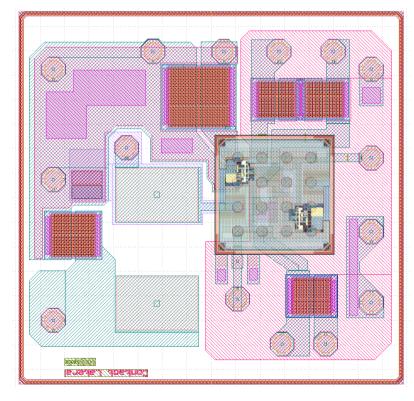
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Primary PLS results









Perspectives

- Waiting for silicon delivery
- Multi-chip test board
- **Verification of limits of robustness**

- Multi-phase design
- **Optimized IC layout**
- **Optimized interposer layout**